

Green's Function

1. What is Green's Function:

As I have shown before, if we take Green's function as generalized function related to linear operator L , we have

$$L(G) = \delta$$

And if $L(y) = f$, we can obtain that

$$y = f * \delta$$

Now for convenience, we define that

$$L G(x, t) = \delta(x - t)$$

And there's $y = \int G(x, t) f(t) dt$

$$\text{Since } Ly(x) = \int L G(x, t) f(t) dt = \int \delta(x - t) f(t) dt = f(x)$$

Notice that we haven't taken boundary condition into account. If there's related items in y (like $\iint_{\Sigma} \psi(\vec{r}_0) \frac{\partial G(\vec{r}, \vec{r}_0)}{\partial n_0} dA_0$), $Ly(x)$ won't be influenced at all, while boundary condition could be met now.

~~2.1~~
2. One dimension problems.

2.1 Some properties

Now we will think about the problem:

$$Ly = \frac{d}{dx} \left[p(x) \frac{dy}{dx} \right] + q(x) \cdot y = f(x)$$

Here we have to deal with the equation:

$$\frac{d}{dx} \left[p(x) \frac{dG(x,t)}{dx} \right] + q(x) G(x,t) = \delta(x-t)$$

And we integrate it from $(x-\epsilon)$ to $(x+\epsilon)$:

$$p(x) \cdot \frac{dG(x,t)}{dx} \Big|_{t-\epsilon}^{t+\epsilon} + \int_{t-\epsilon}^{t+\epsilon} q(x) G(x,t) dx =$$

We can't accept that $G(x,t)$ isn't continuous, but if it's acceptable if $\frac{dG(x,t)}{dx}$ is discontinuous. Thus,

$$\lim_{\epsilon \rightarrow 0^+} \left[\frac{dG(x,t)}{dx} \Big|_{x=t+\epsilon} - \frac{dG(x,t)}{dx} \Big|_{x=t-\epsilon} \right] = \frac{1}{p(t)}$$

Then we will talk about the expansions of $G(x,t)$ in the eigenfunctions of operator L . Of course, L have to be Hermitian and consequently its eigenfunctions could be chosen orthonormal.

That is: $L \psi_n(x) = \lambda_n \psi_n(x)$, $\langle \psi_n | \psi_m \rangle = \delta_{nm}$

Notice that $\psi_n(x)$ is complete, which means

$$|f\rangle = \sum_n \frac{\langle \psi_n | f \rangle}{\langle \psi_n | \psi_n \rangle} |\psi_n\rangle$$

$$\text{That's } \delta(x-t) = \sum_m \psi_m(x) \psi_m^*(t)$$

$$\text{(Proof: } \langle x' | x \rangle = \sum_n \frac{\langle \psi_n | x \rangle}{\langle \psi_n | \psi_n \rangle} \langle x' | \psi_n \rangle = \sum_n \psi_n(x') \psi_n^*(x) \text{)}$$

$$\text{Assume that } G(x,t) = \sum_{mn} g_{nm} \psi_n(x) \psi_m^*(t)$$

$$L G = \delta$$

$$\therefore L \sum g_{nm} \psi_n(x) \psi_m^*(t) = \sum_m \psi_m(x) \psi_m^*(t)$$

$$\therefore \sum \lambda_n g_{nm} \psi_n(x) \psi_m^*(t) = \sum \psi_m(x) \psi_m^*(t)$$

$$\therefore G(x,t) = \sum_n \frac{\psi_n^*(t) \psi_n(x)}{\lambda_n}$$

Thus, it's obvious that $G(x,t) = G(t,x)^*$

Example:
$$\begin{cases} L y = \frac{d^2 y}{dx^2} + y = f(x) \\ y(0) = 0 \\ y'(0) = 0 \end{cases} \Rightarrow \begin{cases} \frac{d^2 G(x,t)}{dx^2} + G(x,t) = \delta(x-t) \\ G(0,t) = 0 \\ G'(0,t) = 0 \end{cases}$$

Notice that Green's function for $x < t$ is $G(x,t) = 0$

As $y(0) = 0, y'(0) = 0 \Rightarrow G(0,t) = 0; G'(0,t) = 0$

But when $x > t$, it's not 0.

Assume that it's $G(x,t) = G_1(t) \sin x + G_2(t) \cos x, \pi > 0$

and $\begin{cases} G(t-,t) = G(t+,t) \\ \frac{\partial G}{\partial x}(t+,t) - \frac{\partial G}{\partial x}(t-,t) = \frac{1}{p(t)} = 1 \end{cases}$

$$\frac{\partial G}{\partial x}(t+,t) - \frac{\partial G}{\partial x}(t-,t) = \frac{1}{p(t)} = 1$$

$$\therefore G(x,t) = \cos t \sin x - \sin t \cos x = \sin(x-t), \quad x > t$$

Thus, $y(x) = \int_0^{\infty} G(x,t) f(t) dt = \int_0^x \sin(x-t) f(t) dt$

3. Green's function without boundary conditions or with boundary conditions

3.1 Wave Equation

Now we will talk about the equations:

$$\begin{cases} \frac{\partial^2 w}{\partial t^2} = a^2 \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) \\ w|_{t=0} = \phi(x, y, z) \\ \left. \frac{\partial w}{\partial t} \right|_{t=0} = \psi(x, y, z) \end{cases}$$

Notice that it's different from previous content. The previous are mainly about the influence of source. But note that it's wave equation now, so the transmission of the wave also ~~counts~~ counts. Note that due to superposition principle, we can divide it into two set of equations

Assume that $w(\vec{r}, t) = u(\vec{r}, t) + v(\vec{r}, t)$

$$\text{and } \begin{cases} \frac{\partial^2 u}{\partial t^2} = a^2 \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) \\ u|_{t=0} = 0 \\ \left. \frac{\partial u}{\partial t} \right|_{t=0} = \psi(x, y, z) \end{cases} \quad \textcircled{1}$$

$$\begin{cases} \frac{\partial^2 v}{\partial t^2} = a^2 \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) \\ v|_{t=0} = \phi(x, y, z) \\ \left. \frac{\partial v}{\partial t} \right|_{t=0} = 0 \end{cases} \quad \textcircled{2}$$

For $\textcircled{1}$, we should have the solution

$$u(\vec{r}, t) = \iiint_{\infty} \psi(\vec{r}_0) G(\vec{r}, \vec{r}_0, t) d\vec{r}_0$$

And G is aimed to the influence of $\frac{\partial u}{\partial t}$. So we have

$$\left\{ \begin{array}{l} \frac{\partial^2 G}{\partial t^2} = a^2 \left(\frac{\partial^2 G}{\partial x^2} + \frac{\partial^2 G}{\partial y^2} + \frac{\partial^2 G}{\partial z^2} \right) \\ G|_{t=0} = 0 \\ \frac{\partial G}{\partial t} \Big|_{t=0} = \delta(x-x_0) \delta(y-y_0) \delta(z-z_0) \end{array} \right.$$

After Fourier transformation, we have

$$G(\vec{r}, t) = \frac{1}{4\pi a t} [\delta(r - at) - \delta(r + at)] \quad , \quad r = |\vec{r} - \vec{r}_0|$$

notice that $t > 0$

$$\therefore G(\vec{r}, t) = \frac{1}{4\pi a} \frac{\delta(|\vec{r} - \vec{r}_0| - at)}{|\vec{r} - \vec{r}_0|}$$

$$\therefore u(\vec{r}, t) = \frac{1}{4\pi a} \iiint_{\infty} \psi(\vec{r}_0) \frac{\delta(|\vec{r} - \vec{r}_0| - at)}{|\vec{r} - \vec{r}_0|} d\vec{r}_0$$

As for v , we have

$$\left\{ \begin{array}{l} \frac{\partial^2 v}{\partial t^2} = a^2 \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) \quad (a) \\ v|_{t=0} = \phi(x, y, z) \quad (b) \\ \frac{\partial v}{\partial t} \Big|_{t=0} = 0 \quad (c) \end{array} \right.$$

Now we set

$$\left\{ \begin{array}{l} \frac{\partial^2 h}{\partial t^2} = a^2 \left(\frac{\partial^2 h}{\partial x^2} + \frac{\partial^2 h}{\partial y^2} + \frac{\partial^2 h}{\partial z^2} \right) \\ h|_{t=0} = 0 \\ \frac{\partial h}{\partial t} \Big|_{t=0} = \phi(x, y, z) \end{array} \right.$$

we have $v = \frac{\partial h}{\partial t}$

Obviously (a) and (b) is satisfied by $\frac{\partial h}{\partial t}$.

$$\begin{aligned} \text{Then } \frac{\partial v}{\partial t} &= \frac{\partial h}{\partial t^2} = a^2 \nabla^2 h(x, y, z, t) \Big|_{t=0} = a^2 \nabla^2 h(x, y, z, 0) \\ &= a^2 \nabla^2 \sigma = 0 \end{aligned}$$

$$\therefore v = \frac{\partial h}{\partial t} = \frac{\partial}{\partial t} \iiint \phi(\vec{r}_0) G(\vec{r}, \vec{r}_0, t) d\vec{r}_0$$

$$\begin{aligned} \therefore u(\vec{r}, t) &= \frac{1}{4\pi a} \left[\frac{\partial}{\partial t} \iiint \phi(\vec{r}_0) \frac{\delta(|\vec{r}-\vec{r}_0|-at)}{|\vec{r}-\vec{r}_0|} d\vec{r}_0 \right. \\ &\quad \left. + \frac{1}{4\pi a} \iiint \psi(\vec{r}_0) \frac{\delta(|\vec{r}-\vec{r}_0|-at)}{|\vec{r}-\vec{r}_0|} d\vec{r}_0 \right] \end{aligned}$$

3.2 Poisson equation:

We know that $\iint (\mathbf{u} \cdot \nabla v - \nabla u \cdot \mathbf{v}) \cdot d\mathbf{s} = \iiint (u \nabla^2 v - v \nabla^2 u) dv$

As before, we have $\nabla^2 v(\vec{r}, \vec{r}_0) = \delta(\vec{r} - \vec{r}_0)$

and $\nabla^2 u = f(\vec{r})$

$$\therefore u(\vec{r}_0) = \iiint_V v(\vec{r}, \vec{r}_0) f(\vec{r}) dv - \iint_{\Sigma} \left[v(\vec{r}, \vec{r}_0) \frac{\partial u(\vec{r})}{\partial n} - u(\vec{r}) \frac{\partial v(\vec{r}, \vec{r}_0)}{\partial n} \right] d\mathbf{s}$$

Then we will talk about boundary conditions

(i) for Dirichlet condition, we know the distribution of u on Σ_1 ,

and if we require that $v|_{\Sigma} = 0$, then the item related to

$\frac{\partial u}{\partial n}$ would be 0.

and now we have;

$$u(\vec{r}_0) = \iiint_V G(\vec{r}, \vec{r}_0) f(\vec{r}) dV + \iint_{\Sigma} \psi(\vec{r}) \frac{\partial G(\vec{r}, \vec{r}_0)}{\partial n} dS$$

If the boundary condition is

$$\left[\alpha \frac{\partial u}{\partial n} + \beta u \right]_{\Sigma} = \psi$$

We will give v the same: $\left[\alpha \frac{\partial v}{\partial n} + \beta v \right]_{\Sigma} = 0$

$$\begin{aligned} \text{Thus, } v \frac{\partial u}{\partial n} - u \frac{\partial v}{\partial n} &= \frac{1}{\alpha} \left[(\alpha v \frac{\partial u}{\partial n} + \beta uv) - (\alpha u \frac{\partial v}{\partial n} + \beta uv) \right] \\ &= \frac{1}{\alpha} v \psi \end{aligned}$$

$$\therefore u(\vec{r}_0) = \iiint_V v(\vec{r}, \vec{r}_0) f(\vec{r}) dV - \frac{1}{\alpha} \iint_{\Sigma} v(\vec{r}, \vec{r}_0) \psi(\vec{r}) dS$$

As for Neumann condition, we hope that

$$\begin{cases} \nabla^2 v = \delta(\vec{r} - \vec{r}_0) (*) \\ \left. \frac{\partial v}{\partial n} \right|_{\Sigma} = 0 \end{cases}, \text{ and thus we have}$$

$$u(\vec{r}_0) = \iiint_V v(\vec{r}, \vec{r}_0) f(\vec{r}) dV - \iint_{\Sigma} v(\vec{r}, \vec{r}_0) \psi(\vec{r}) dS \quad \left(\frac{\partial u(\vec{r})}{\partial n} = \psi(\vec{r}) \right)$$

If the solution domain is semi-infinite, it's ok. But what if it's closed? You will find that (*) has no solution!

$\nabla^2 v = \delta(\vec{r} - \vec{r}_0)$ and $\left. \frac{\partial v}{\partial n} \right|_{\Sigma} = 0$ is contradictory

Now we have to introduce

$$\nabla^2 G = \delta(x-x_0) \delta(y-y_0) \delta(z-z_0) - \frac{1}{V_T} \rightarrow \text{volume/area} \dots$$

$$\text{and } \frac{\partial G}{\partial n} \Big|_{\Sigma} = 0$$

and we have

$$u(\vec{r}_0) = \iiint_{V_T} G(\vec{r}, \vec{r}_0) f(\vec{r}) d\vec{r} - \iint_{\Sigma} G(\vec{r}, \vec{r}_0) \psi(\vec{r}) ds + \frac{\iiint_{V_T} u(\vec{r}) d\vec{r}}{V_T}$$

that's the same as adding a constant. And we can find it out easily

Now we will talk about boundary conditions. Now we have to generalize Green's function. For the equation

$$a_{11} u_{xx} + 2a_{12} u_{xy} + a_{22} u_{yy} + b_1 u_x + b_2 u_y + cu = 0$$

We denote it as $Lu = 0$

If there's M such that

$$vLu - uMv = \frac{\partial X}{\partial x} + \frac{\partial Y}{\partial y}, \text{ and } X = X(x, y), Y = Y(x, y)$$

we could call M as adjoint operator of L , and vice versa.

If $M=L$, then it's self-adjoint operator.

Now we have

$$\iint_{\Sigma} (vLu - uMv) ds = \int_{\Sigma} [X \cos \langle \vec{n}, \vec{x} \rangle + Y \cos \langle \vec{n}, \vec{y} \rangle] ds$$

This generalized Green's function.

Example. $u_{tt} - a^2 \nabla^2 u = -f(\vec{r}) e^{i\omega t}$

we assume that ~~the~~ $U(\vec{r}, t) = u(\vec{r}) e^{i\omega t}$,

and there's $(a^2 + a^2 \nabla^2) u = -f(\vec{r})$

The green's function is, in fact

$$G(\vec{r}, \vec{r}_0) = \frac{1}{4\pi} \frac{e^{i\frac{\omega}{a} |\vec{r} - \vec{r}_0|}}{|\vec{r} - \vec{r}_0|}$$

and we have

$$u(\vec{r}) = \frac{1}{4\pi} \iint_{\Sigma} \left[\frac{e^{i\frac{\omega}{a} |\vec{r} - \vec{r}_0|}}{|\vec{r} - \vec{r}_0|} \frac{\partial y}{\partial n} - u \frac{\partial}{\partial n} \frac{e^{i\frac{\omega}{a} |\vec{r} - \vec{r}_0|}}{|\vec{r} - \vec{r}_0|} \right] ds_0 \\ - \frac{1}{4\pi} \iiint_{\tau} \frac{e^{i\frac{\omega}{a} |\vec{r} - \vec{r}_0|}}{|\vec{r} - \vec{r}_0|} f(\vec{r}_0) dV_0$$

3.3 Green Function with time

Now we have
$$\begin{cases} u_{tt} - a^2 \nabla^2 u = f(\vec{r}, t) \\ \left(a \frac{\partial y}{\partial n} + \beta u \right) \Big|_{\Sigma} = \theta(\mathbb{M}, t) \\ u|_{t=0} = \psi(\vec{r}), \quad u_t|_{t=0} = \Psi(\vec{r}) \end{cases}$$

We assume that
$$\begin{cases} G_{tt} - a^2 \nabla^2 G = \delta(\vec{r} - \vec{r}_0) \delta(t - t_0) \\ a \frac{\partial G}{\partial n} + \beta G \Big|_{\Sigma} = 0 \\ G|_{t=0} = 0, \quad G_t|_{t=0} = 0 \end{cases}$$

Notice that the symmetry is:

$$G(\vec{r}, t; \vec{r}_0, t_0) = G(\vec{r}_0, -t_0; \vec{r}, -t)$$

So we have to:
$$\begin{cases} U_{t_0 t_0}(\vec{r}_0, t_0) - a^2 \nabla_0^2 U(\vec{r}_0, t_0) = f(\vec{r}_0, t_0) \\ a \frac{\partial U_0}{\partial n_0} + \beta U_0 = \Theta(M_0, t_0) \\ U(\vec{r}_0, t_0)|_{t_0=0} = \psi(\vec{r}_0), U_t(\vec{r}_0, t_0)|_{t_0=0} = \psi'(\vec{r}_0) \end{cases}$$

and
$$\begin{cases} G_{t_0 t_0}(\vec{r}, t; \vec{r}_0, t_0) - a^2 \nabla_0^2 G(\vec{r}, t; \vec{r}_0, t_0) = \delta(\vec{r} - \vec{r}_0) \delta(t - t_0) \\ [a \frac{\partial G(\vec{r}, t; \vec{r}_0, t_0)}{\partial n_0} + \beta G(\vec{r}, t; \vec{r}_0, t_0)]|_{\Sigma} = 0 \\ G(\vec{r}, t; \vec{r}_0, t_0)|_{t_0=0} = 0, G_{t_0}(\vec{r}, t; \vec{r}_0, t_0)|_{t_0=0} = 0 \end{cases}$$

$$\therefore \iint_V \int_0^{t+\epsilon} (G U_{t_0 t_0} - U G_{t_0 t_0}) dV_0 dt_0 - a^2 \iint_V \int_0^{t+\epsilon} (G \Delta_0 U - U \Delta_0 G) dV_0 dt_0$$

$$= \iint_V \int_0^{t+\epsilon} G(\vec{r}, t; \vec{r}_0, t_0) f(\vec{r}_0, t_0) dV_0 dt_0 - \iint_V \int_0^{t+\epsilon} U \delta(\vec{r} - \vec{r}_0) \delta(t - t_0) dV_0 dt_0$$

$(\epsilon \rightarrow 0) \quad \epsilon \cdot \int \delta(t - t_0) dt_0$ is certain

$$\therefore U(\vec{r}, t) = \iint_V \int_0^{t+\epsilon} G(\vec{r}, t; \vec{r}_0, t_0) f(\vec{r}_0, t_0) dV_0 dt_0 - \iint_V \int_0^{t+\epsilon} (G U_{t_0 t_0} - U G_{t_0 t_0}) dV_0 dt_0 + a^2 \iint_V \int_0^{t+\epsilon} (G \Delta_0 U - U \Delta_0 G) dV_0 dt_0$$

Notice that $G U_{t_0 t_0} - U G_{t_0 t_0} = \frac{d}{dt_0} (G U_{t_0} - U G_{t_0})$

and when $t < t_0$, $G=0$, $G_{t_0}=0$

So we can obtain:

$$U(\vec{r}, t) = \iint_V \int_0^t G(\vec{r}, t; \vec{r}_0, t_0) f(\vec{r}_0, t_0) dV_0 dt_0 + a^2 \iint_V \int_0^t (G \frac{\partial U}{\partial n_0} - U \frac{\partial G}{\partial n_0}) dS_0 dt_0 - \iint_V [G U_{t_0} - U G_{t_0}]|_{t_0=0} dV_0$$

As for the problem

$$\begin{cases} u_t - a^2 \Delta u = f(\vec{r}, t) \\ \left[a \frac{\partial u}{\partial n} + \beta u \right]_{\Sigma} = \theta(M, t) \\ u|_{t=0} = \psi(\vec{r}) \end{cases}$$

We can obtain that

$$\begin{aligned} u(\vec{r}, t) = & \iiint_{\tau} \int_0^t G(\vec{r}, t, \vec{r}_0, t_0) f(\vec{r}_0, t_0) dV_0 dt_0 \\ & + a^2 \iint_{\Sigma} \int_0^t \left(G \frac{\partial u}{\partial n_0} - u \frac{\partial G}{\partial n_0} \right) dS_0 dt_0 \\ & + \iiint_{\tau} [u G]_{t_0=0} dV_0 \end{aligned}$$

4. How to find out the function

4.1 One dimension $(a \leq x \leq b)$

Now we will talk ~~out~~ about the question where L

is the form of $\frac{d}{dx} \left[P(x) \frac{d}{dx} \right] + q(x)$ with homogeneous boundary condition. As is shown before, we have

$$\begin{cases} G(t_-, t) = G(t_+, t) \\ \left[\frac{\partial G}{\partial x}(t_+, t) - \frac{\partial G}{\partial x}(t_-, t) \right] = \frac{1}{P(t)} = 1 \end{cases}$$

Given $y(x) = \int_a^b G(x, t) f(t) dt$, if boundary condition is

$Ly = 0$ (L is linear), it's obvious that G also ~~s~~ satisfy the condition.

now we set that $y_1(x)$ is the solution to $L = 0$ and also satisfies the boundary condition ~~at~~ at $x=a$; while $y_2(x)$ satisfies the boundary condition at $x=b$.

So the most general $G(x,t)$ should be

$$G(x,t) = \begin{cases} y_1(x)h_1(t), & x < t \\ y_2(x)h_2(t), & x > t \end{cases}$$

It satisfies boundary condition and the former equations as well. So we have $G(x,t) = \begin{cases} Ay_1(x)y_2(t), & x < t \\ Ay_2(x)y_1(t), & x > t \end{cases}$

$$\text{Thus, } A [y_2'(t)y_1(t) - y_1'(t)y_2(t)] = \frac{1}{P(t)}$$

$$\text{and } A = \frac{1}{P(t) \cdot [y_2'(t)y_1(t) - y_1'(t)y_2(t)]}$$

$$\text{Notice that } \begin{cases} P(t)y_1''(t) + P'(t)y_1'(t) + q(t)y_1(t) = 0 \\ P(t)y_2''(t) + P'(t)y_2'(t) + q(t)y_2(t) = 0 \end{cases}$$

$$\begin{aligned} \therefore P'(t) \cdot (y_2'(t)y_1(t) - y_1'(t)y_2(t)) + P(t) \frac{d}{dt} (y_2'(t)y_1(t) - y_1'(t)y_2(t)) &= 0 \\ \therefore y_2'(t)y_1(t) - y_1'(t)y_2(t) &= \frac{C}{P(t)}, \text{ and } A = C \text{ (there's no } t) \end{aligned}$$

and we have

$$y(x) = Ay_2(x) \int_a^x y_1(t)f(t)dt + Ay_1(x) \int_0^x y_2(t)f(t)dt$$

(*) verify that it is the solution

2 More dimensions

4.2.1 Electric image method

Now we will focus on Poisson's equation with Dirichlet Conditions

That is to say,
$$\begin{cases} \Delta G = \delta(\vec{r} - \vec{r}_0) \\ G|_{\Sigma} = 0 \end{cases}$$

And when it comes to electrostatic problems, we have

$$\begin{cases} \Delta \Psi = -\frac{\rho}{\epsilon_0} \delta(\vec{r} - \vec{r}_0) \quad (\text{point charge}) \\ \Psi|_{\Sigma} = 0 \end{cases}$$

They are literally the same! So we can apply the method to Green's function. ($\epsilon_0 = 1, \rho = -1$)

Example. inside a ball $r=a$.
$$\begin{cases} \Delta^2 u = 0 \quad (r < a) \\ u|_{r=a} = f(\theta, \varphi) \end{cases}$$



Solution: taking use of electric image method, and take $\begin{cases} \epsilon_0 = 1 \\ \rho = -1 \end{cases}$

we have
$$G(\vec{r}_1, \vec{r}_0) = -\frac{1}{4\pi} \frac{1}{|\vec{r}_1 - \vec{r}_0|} + \frac{a}{r_0} \frac{1}{4\pi} \frac{1}{|\vec{r}_1 - \vec{r}_1|}, \quad \vec{r}_1 = \frac{a^2}{r_0^2} \vec{r}_0$$

Now we have
$$u(\vec{r}) = \iiint_V G(\vec{r}_1, \vec{r}_0) f(\vec{r}_0) dV_0 + \iint_{\Sigma} \Psi(\vec{r}_0) \frac{\partial G(\vec{r}, \vec{r}_0)}{\partial n_0} dS_0$$

And also we have

$$\frac{\partial G}{\partial n_0} \Big|_{\Sigma} = \frac{a^2 - r^2}{4\pi a |\vec{r} - \vec{r}_0|^3}$$

$$u = \frac{q}{4\pi} \int_0^\pi \int_0^{2\pi} f(\theta_0, \varphi_0) \frac{a^2 - r^2}{(a^2 - 2ar_0 \cos \theta + r_0^2)^{\frac{3}{2}}} \sin \theta_0 d\theta_0 d\varphi_0$$

$$\text{(or } \frac{q}{4\pi a} \int_0^\pi \int_0^{2\pi} f(\theta_0, \varphi_0) \cdot \frac{(a^2 - r^2)a^2}{|\vec{r} - \vec{r}_0|^3} \sin \theta_0 d\theta_0 d\varphi_0)$$

4.2.2 Impulse Theorem:

Now we will talk about the Green function in the form of wave ~~func~~ equation or heat conduction equation.

$$\text{for example: } \begin{cases} G_{tt} - a^2 G_{xx} = \delta(x - \xi) \delta(t - \tau) \\ G|_{t=0} = 0 \quad G_t|_{t=0} = 0 \end{cases}$$

It could be transformed into

$$\begin{cases} G_{tt} - a^2 G_{xx} = 0 \\ G|_{t=0} = 0 \\ G_t|_{t=0} = \delta(x - \xi) \end{cases}, \text{ and we have}$$

$$G(x, t; \xi, \tau) = \frac{1}{2a} \int_{x-a(t-\tau)}^{x+a(t-\tau)} \delta(\xi_0 - \xi) d\xi_0 = \begin{cases} 0, & \xi < x - a(t-\tau) \text{ or } x + a(t-\tau) < \xi \\ \frac{1}{2a}, & x - a(t-\tau) < \xi < x + a(t-\tau) \end{cases}$$

$$\text{and } u(x, t) = \int_0^t \int_{\xi}^{x+a(t-\tau)} \frac{1}{2a} f(\xi, \tau) d\xi d\tau$$

4.2.3 Other ways

Example, $\nabla^2 G(\vec{r}_1, \vec{r}_2) + k^2 G(\vec{r}_1, \vec{r}_2) = \delta(\vec{r}_1 - \vec{r}_2)$

Solution: we set $G(\vec{r}_1, \vec{r}_2) = y(r)$, $r = |\vec{r}_1 - \vec{r}_2|$

$$\therefore \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial y}{\partial r} \right) + k^2 y = \delta(r)$$

Now we assume that $y = \frac{f}{r}$, and we

get
$$\frac{d^2 f}{dr^2} + k^2 f = \delta(r)$$

$$\therefore \frac{d^2 f}{dr^2} + k^2 f = 0, \text{ and } f = A \exp(ikr)$$

Given $\iiint_{\text{IR}^3} \frac{1}{r} y(r) dV = -\frac{A}{r^2} \cdot 4\pi r = 1 \quad \therefore A = -\frac{1}{4\pi}$

and $y = -\frac{\exp[ik|\vec{r}_1 - \vec{r}_2|]}{4\pi|\vec{r}_1 - \vec{r}_2|}$ that's Green's function.