

张量与微分形式

1. Tensor Analysis

1.1. Introduction GR, ED, Material

Scalar - 0

vector - 1, Dimension, transform

tensor of rank  $k$ ,  $d$ -dimension  
 $\rightarrow$   $k$  indices,  $n=1, 2, \dots, d^k$  components.

transformed in a special manner.  
 Components

1.2. Covariant and Contravariant Tensor (Cartesian)

$$A_i = \sum_j (e_i \cdot e_j) A_j = \sum_j \frac{\partial x_j}{\partial x_i} A_j \quad \therefore \sum_j \frac{\partial x_j}{\partial x_i} A_j$$

$$(\nabla \varphi)_i = \frac{\partial \varphi}{\partial x_i} = \sum_j \frac{\partial x_j}{\partial x_i} \frac{\partial \varphi}{\partial x_j} = \sum_j \frac{\partial x_j}{\partial x_i} \frac{\partial \varphi}{\partial x_j}$$

$$(A')^i = \frac{\partial x^i}{\partial x^j} A_j \quad \text{Contravariant vector}$$

$$A_i = \frac{\partial x^j}{\partial x^i} A_j \quad (\nabla \varphi)_i = \frac{\partial \varphi}{\partial x^i} \quad \text{Covariant vector}$$

1.3. Tensor of rank 2.

$$(A')^{ij} = \frac{\partial x^i}{\partial x^k} \frac{\partial x^j}{\partial x^l} A^{kl}$$

$$(A')^i_j = \frac{\partial x^i}{\partial x^k} \frac{\partial x^k}{\partial x^l} A^k_l$$

$$(A')_{ij} = \frac{\partial x^k}{\partial x^i} \frac{\partial x^l}{\partial x^j} A_{kl}$$

Cartesian coordinate  
 All the same

$$(A')^{ij} = S_{ik} A^{kl} (S^T)^j_l \Leftrightarrow A' = S A S^T \Leftrightarrow \vec{A}' = S^T \vec{A} S$$

Similarity transformation  
 Congruent transformation

1.4. Addition and Subtraction of tensors

$$A + B = C$$

$$A^{ij} + B^{ij} = C^{ij}$$

Symmetry.

$$A^{mn} = A^{nm} \quad \text{symmetric}$$

$$A^{mn} = -A^{nm} \quad \text{antisymmetric}$$

$$A^{mn} = \frac{1}{2} (A^{mn} + A^{nm}) + \frac{1}{2} (A^{mn} - A^{nm})$$

1.5. Isotropic tensor

$$\delta^k_l = \frac{\partial x^k}{\partial x^k} \frac{\partial x^l}{\partial x^l} = \left( \frac{\partial x^k}{\partial x^k} \right) \frac{\partial x^k}{\partial x^l} \frac{\partial x^l}{\partial x^k} = \frac{\partial x^k}{\partial x^k} = \delta^k_k$$

And it's isotropic.

1.6. Contraction

$$\vec{A} \cdot \vec{B} = A^i B_i$$

$$(B')^i_i = \frac{\partial x^i}{\partial x^k} \frac{\partial x^k}{\partial x^l} B^k_l = \frac{\partial x^k}{\partial x^k} B^k_l = \delta_{kl} B^k_l = B^k_k$$

Scalar, trace is invariant

$$\text{tr}(P^{-1} A P) = \text{tr}(A P P^{-1}) = \text{tr}(A)$$

1.7. Direct Product.

$$C^{ij}_{km} = A^i_k B^j_{lm}, \quad F^{ij}_{kl} = A^i_j B^k_{lm}$$

$$(\nabla \vec{E}) = \partial_i E_j$$

$$(\vec{A} \cdot \nabla) \vec{B} = A_i \partial_i B_j$$

Example 1.

$$C^i_j = a^i_k b^k_j = \frac{\partial x^k}{\partial x^i} a_k \frac{\partial x^i}{\partial x^l} b^l_j = \frac{\partial x^k}{\partial x^i} \frac{\partial x^i}{\partial x^l} c^l_k$$

二阶 Tensor

Generally,

$$\frac{\partial x^i}{\partial (x')^i} \neq \left( \frac{\partial (x')^j}{\partial x^i} \right)^{-1}$$

Cartesian system

$$\frac{\partial x^i}{(\partial x')^i} = \frac{\partial (x')^j}{\partial x^i}$$

1.8. Quotient rule

$$K_i A^i = B$$

$$K_{ij} A^i = B_{jk}$$

if equation holds in all transformed coordinate system, then  $K$  is a tensor

$$K_i^j A_j = B_i \rightarrow (K')_i^j A_j' = B_i'$$

$$B_i' = \frac{\partial x^m}{\partial (x')^i} B_m = \frac{\partial x^m}{\partial (x')^i} K_m^j A_j$$

$$= \frac{\partial x^m}{\partial (x')^i} K_m^j \frac{\partial x^n}{\partial x^i} A_n'$$

$$= \frac{\partial x^m}{\partial (x')^i} \frac{\partial x^j}{\partial x^m} K_m^n A_j' = (K')_i^j A_j'$$

$$\Rightarrow \left[ (K')_i^j - \frac{\partial x^m}{\partial (x')^i} \frac{\partial x^j}{\partial x^m} K_m^n \right] A_j' = 0$$

Example 2

$$\left[ \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right] A^\mu = J^\mu$$

Scalar  $\uparrow$  Vector

1.9. Spinor | Spin scalar  $\uparrow$  vector  $\uparrow$  spinor  $\uparrow$  spinor

$$\begin{aligned} x &= r \cos \theta & \theta &= \arctan \frac{y}{x} \\ y &= r \sin \theta \\ \frac{\partial x}{\partial \theta} &= -r \sin \theta & \frac{\partial y}{\partial \theta} &= r \cos \theta \\ \frac{\partial x}{\partial r} &= \cos \theta & \frac{\partial y}{\partial r} &= \sin \theta \\ \frac{\partial x}{\partial y} &= -\frac{\tan \theta}{r} & \frac{\partial y}{\partial x} &= \frac{1}{r \cos^2 \theta} \\ \frac{\partial \theta}{\partial y} &= -\frac{1}{r \cos^2 \theta} & \frac{\partial \theta}{\partial x} &= \frac{1}{r \sin^2 \theta} \end{aligned}$$

$$\begin{aligned} \begin{bmatrix} x \\ y \end{bmatrix} &= \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} r \\ \theta \end{bmatrix} \\ \begin{bmatrix} x \\ y \end{bmatrix} &= \begin{bmatrix} \cos \theta & 0 \\ \sin \theta & 0 \end{bmatrix} \begin{bmatrix} r \\ \theta \end{bmatrix} \\ \begin{bmatrix} x \\ y \end{bmatrix} &= \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} r \\ \theta \end{bmatrix} \end{aligned}$$

## 2.1 Pseudovectors dual tensor

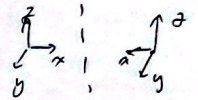
$$A' = SA \quad \leftarrow \text{vector}$$

$$A' = \det(S) SA \quad \leftarrow \text{pseudo vector}$$

$$T \otimes T = P \otimes P = T \quad T \otimes P = P \otimes T = P$$

Example 3.  $\equiv$  阶全反对称不变张量

$$\epsilon_{ijk} = \det(A) \sum_{pqr} a_{ip} a_{jq} a_{kr} \text{ or } \epsilon_{pqr}$$



## 2.2 Dual Tensor

Anti-symmetric tensor  $C$ , associate with  $(\cdot, \cdot)$

a pseudo vector

$$\text{Vector} \rightarrow C_i = \frac{1}{2} \epsilon_{ijk} C^{jk}$$

$$(C_1, C_2, C_3) = (C^{23}, C^{31}, C^{12})$$

$$C = \begin{pmatrix} 0 & \epsilon^{12} & -C^{31} \\ -C^{12} & 0 & C^3 \\ C^{31} & -C^{23} & 0 \end{pmatrix}$$

simply different representation of the same thing

$$V^{ijk} = A^i B^j C^k$$

Hodge dual

$$V = \epsilon_{ijk} V^{ijk}$$

$$\epsilon: T_{i_1 \dots i_p} \mapsto \frac{1}{(n-p)!} \epsilon_{i_1 \dots i_p j_1 \dots j_{n-p}}$$

$$= \begin{vmatrix} A^1 & B^1 & C^1 \\ A^2 & B^2 & C^2 \\ A^3 & B^3 & C^3 \end{vmatrix}$$

$$\left( \frac{1}{n!} \epsilon_{i_1 \dots i_n} \right)$$

## 3. Tensors in general coordinate

### 3.1 Metric tensor

3.1.1 Covariant basis vector  $\hat{e}_i$

$$\hat{e}_i = \frac{\partial x}{\partial x^i} \hat{e}_x + \frac{\partial y}{\partial x^i} \hat{e}_y + \frac{\partial z}{\partial x^i} \hat{e}_z$$

$$\vec{A} = A^1 \hat{e}_1 + A^2 \hat{e}_2 + A^3 \hat{e}_3$$

$$ds^2 = \sum \hat{e}_i dq^i \cdot \hat{e}_j dq^j = \hat{e}_i \cdot \hat{e}_j dq^i dq^j$$

$$\Rightarrow g_{ij} = \hat{e}_i \cdot \hat{e}_j \quad \text{neither unit nor mutually orthogonal}$$

Covariant tensor

$$g^{ik} g_{kj} = g_{jk} g^{ki} = \delta^i_j$$

Use to make connection between contra - co.

$$g_{ij} F^j = F_i \quad , \quad g^{ij} F_j = F^i$$

$$\vec{A} = A^i \hat{e}_i = A^i \delta_i^k \hat{e}_k = (A^i g_{ij}) (g^{jk} \hat{e}_k) = A_j \hat{e}^j$$

### 3.1.2 Contra - Co Bases

$$\hat{e}_i = \frac{\partial q^j}{\partial x^i} \hat{e}_x + \dots \quad \leftarrow \text{Contra basis vector}$$

$$\hat{e}^i \cdot \hat{e}_j = \frac{\partial q^i}{\partial x^k} \frac{\partial x^k}{\partial q^j} + \dots = \delta^i_j$$

$$\hat{e}^i \cdot \hat{e}^j (\hat{e}_j \cdot \hat{e}_k) = \delta^i_k$$

$$\left( \frac{\partial q^i}{\partial x^k} \frac{\partial q^j}{\partial x^l} + \dots \right) \left( \frac{\partial x^k}{\partial q^j} \frac{\partial x^l}{\partial q^i} + \dots \right) = \delta^i_k$$

$$\frac{\partial q^i}{\partial x^k} \frac{\partial q^j}{\partial x^l} \frac{\partial x^k}{\partial q^j} \frac{\partial x^l}{\partial q^i}$$

$$\Rightarrow (g^{ij}) g_{ik} = \delta^j_k$$

$$g^{ij} = \hat{e}^i \cdot \hat{e}^j \rightarrow \boxed{g^{ij} \hat{e}_j = \hat{e}^i}$$

### Example 4.

$$x = r \sin \theta \cos \varphi, \quad y = r \sin \theta \sin \varphi, \quad z = r \cos \theta$$

$$\begin{aligned} \hat{e}_r &= & g_{11} &= \\ \hat{e}_\theta &= & g_{22} &= \\ \hat{e}_\varphi &= & g_{33} &= \\ \hat{e}^r &= & g^{11} &= \\ \hat{e}^\theta &= & g^{22} &= \\ \hat{e}^\varphi &= & g^{33} &= \end{aligned} \Rightarrow g_{ij} = \begin{pmatrix} 1 & & \\ & r^2 & \\ & & r^2 \sin^2 \theta \end{pmatrix}$$

$$g^{ij} = \begin{pmatrix} 1 & & \\ & r^{-2} & \\ & & (r \sin \theta)^{-2} \end{pmatrix}$$

$$\vec{A} \cdot \vec{B} = (A^i \hat{e}_i) \cdot (B_j \hat{e}^j) = A^i B_j (\hat{e}_i \cdot \hat{e}^j) = A^i B_i$$

$$\begin{aligned} (\vec{\nabla} \psi)_i &= \frac{\partial \psi}{\partial q^i} \frac{\partial q^i}{\partial x^j} = \frac{\partial \psi}{\partial x^j} \hat{e}^j = \frac{\partial \psi}{\partial x^j} g^{jk} \hat{e}_k = \frac{\partial \psi}{\partial x^j} \hat{e}_k \end{aligned}$$

### 3.2. Covariant Derivatives

$$(V^i)' = \frac{\partial x^i}{\partial q^k} V^k$$

$$\frac{\partial V^i}{\partial q^j} = \frac{\partial x^i}{\partial q^k} \frac{\partial V^k}{\partial q^j} + \frac{\partial^2 x^i}{\partial q^j \partial q^k} V^k$$

$$\Rightarrow \frac{\partial \vec{V}^i}{\partial q^j} = \frac{\partial V^k}{\partial q^j} \hat{e}_k + V_k \frac{\partial \hat{e}_k}{\partial q^j}$$

$$\Rightarrow \frac{\partial V^i}{\partial q^j} = \frac{\partial V^k}{\partial q^j} \hat{e}_k + V^k \Gamma_{jk}^m \hat{e}_m$$

$$= \left( \frac{\partial V^k}{\partial q^j} + V^m \Gamma_{jm}^k \right) \hat{e}_k$$

$$V_{;j}^k = \frac{\partial V^k}{\partial q^j} + V^m \Gamma_{jm}^k$$

$$\Rightarrow \frac{\partial V^i}{\partial q^j} = V_{;j}^k \hat{e}_k$$

$$\begin{aligned} \vec{r} &= x \hat{e}_1 + y \hat{e}_2 = r \hat{e}^1 + 0 \hat{e}^2 \\ \dot{\vec{r}} &= \frac{\partial x}{\partial t} \hat{e}_1 + \frac{\partial y}{\partial t} \hat{e}_2 = \dot{x} \hat{e}_1 + \dot{y} \hat{e}_2 \end{aligned}$$

$$\frac{\partial \hat{e}_k}{\partial q^j} = \Gamma_{jk}^m \hat{e}_m$$

$\Gamma_{jk}^m$  Christoffel Symbols of the 2<sup>nd</sup> kind

$$\Gamma_{jk}^m = \hat{e}^m \cdot \frac{\partial \hat{e}_k}{\partial q^j}$$

$$\Gamma_{jk}^m = \Gamma_{kj}^m$$

$$\boxed{\frac{\partial \hat{e}_i}{\partial q^j} = \frac{\partial \hat{e}_i}{\partial q^j}} \quad \text{(Proof Retraction)}$$

$\Rightarrow d\vec{V} = [V_i^k; j dq^j] \hat{E}_i$   $V_i^k$  is a mixed tensor

Covariant

$$V_{ij} = V_i^k g_{jk} = \frac{\partial V_i}{\partial q^j} + V_u^k \Gamma_{ju}^k$$

$$\frac{\partial V_i^k}{\partial q^j} \cdot \Gamma_{jk}^i \text{ 都不是张量}$$

$$\frac{\partial (V_i^k \Gamma_{jk}^i)}{\partial q^l} = \frac{\partial V_i^k}{\partial q^l} \Gamma_{jk}^i + V_u^k \frac{\partial \Gamma_{jk}^i}{\partial q^l} + \Gamma_{ju}^k \frac{\partial V_i^k}{\partial q^l} + \Gamma_{jk}^i \Gamma_{lu}^k V_u^k = 0$$

但  $V_i^k$  是张量

Christoffel symbol of the first kind

$$[ij, k] = g_{mk} \Gamma_{ij}^m = \Gamma_{ij, k}$$

$$= g_{mk} \hat{E}_m \cdot \frac{\partial \hat{E}_i}{\partial q^j} = \hat{E}_k \cdot \frac{\partial \hat{E}_i}{\partial q^j}$$

$$g_{ij} = \hat{E}_i \cdot \hat{E}_j$$

$$\frac{\partial g_{ij}}{\partial q^k} = \frac{\partial \hat{E}_i}{\partial q^k} \cdot \hat{E}_j + \hat{E}_i \cdot \frac{\partial \hat{E}_j}{\partial q^k} = [ik, j] + [jk, i]$$

$$\frac{\partial g_{ik}}{\partial q^j} = [ij, k] + [jk, i]$$

$$\frac{\partial g_{ik}}{\partial q^l} = [li, k] + [kl, j]$$

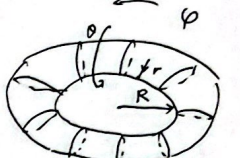
$$\frac{1}{2} \left( \frac{\partial g_{ik}}{\partial q^l} + \frac{\partial g_{il}}{\partial q^k} - \frac{\partial g_{ij}}{\partial q^l} \right) = [ij, k]$$

①  $\Rightarrow g^{nk} [ij, k] = \Gamma_{ij}^n$

$$\Rightarrow \Gamma_{ij}^n = g^{nk} [ij, k] = \frac{1}{2} g^{nk} \left( \frac{\partial g_{jk}}{\partial q^i} + \frac{\partial g_{ik}}{\partial q^j} - \frac{\partial g_{ij}}{\partial q^k} \right)$$

Example 1.

甜甜圈上的黎曼几何



$$H_i = \left| \frac{\partial \vec{r}}{\partial x^i} \right|$$

$$\frac{\partial x}{\partial \theta} = -r \sin \theta \cos \phi \quad \frac{\partial x}{\partial \phi} = -(R+r \cos \theta) \sin \phi$$

$$\frac{\partial x}{\partial \theta} = -r \sin \theta \sin \phi \quad \frac{\partial x}{\partial \phi} = (R+r \cos \theta) \cos \phi$$

$$\frac{\partial z}{\partial \theta} = r \cos \theta \quad \frac{\partial z}{\partial \phi} = 0$$

$$R, r, \theta, \phi$$

$$x = (R+r \cos \theta) \cos \phi$$

$$y = (R+r \cos \theta) \sin \phi$$

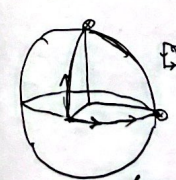
$$z = r \sin \theta$$

$$H_\theta = r, H_\phi = R+r \cos \theta$$

$$g_{\theta\theta} = r^2, g_{\phi\phi} = (R+r \cos \theta)^2, g_{\theta\phi} = g_{\phi\theta} = 0$$

$$g_{\mu\nu} = \begin{bmatrix} r^2 & 0 \\ 0 & (R+r \cos \theta)^2 \end{bmatrix} \quad dV = \sqrt{|g|} dx^1 \dots dx^n$$

Levi-Civita 符号



$$A_{\mu;\nu} = \frac{\partial A_\mu}{\partial x^\nu} - \Gamma_{\mu\nu}^\alpha A_\alpha$$

$$\Gamma_{\mu\nu}^\alpha = \frac{1}{2} g^{\alpha\beta} (g_{\beta\mu, \nu} + g_{\beta\nu, \mu} - g_{\mu\nu, \beta})$$

$$\Gamma_{\mu\nu}^\alpha = \begin{pmatrix} (0, 0), (0, ) \\ ( ), ( ) \end{pmatrix} \quad \Gamma_{11}^1 = \Gamma_{22}^1 = 0 \quad \Gamma_{21}^1 = 0, \Gamma_{22}^1 = \frac{(R+r \cos \theta) \sin \theta}{r}$$

$$\Gamma_{11}^2 = \Gamma_{12}^2 = \Gamma_{21}^2 = \Gamma_{22}^2 = 0$$

$$= 0 = \dots = \dots$$

$$\frac{1}{2} g^{21} (g_{11,2} + g_{12,1} - g_{21,1}) + \frac{1}{2} g^{22} (g_{12,2} + g_{22,1} + g_{21,2})$$

$$= \frac{1}{2} \frac{1}{(R+r \cos \theta)^2} \cdot 2(R+r \cos \theta) \cdot -\sin \theta \cdot r \cdot \checkmark$$

不是方程

$$\nabla_\nu A_\mu = \partial_\nu A_\mu + \Gamma_{\mu\nu}^\alpha A_\alpha = 0$$

$$\partial_\nu A_\mu = \Gamma_{\mu\nu}^\alpha A_\alpha$$

球坐标

$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$


$$z = r \cos \theta$$

$$\frac{\partial x}{\partial r} = \sin \theta \cos \varphi \quad \frac{\partial x}{\partial \theta} = r \cos \theta \cos \varphi \quad \frac{\partial x}{\partial \varphi} = -r \sin \theta \sin \varphi$$

$$\frac{\partial y}{\partial r} = \sin \theta \sin \varphi \quad \frac{\partial y}{\partial \theta} = r \sin \theta \cos \varphi \quad \frac{\partial y}{\partial \varphi} = r \sin \theta \cos \varphi$$

$$\frac{\partial z}{\partial r} = \cos \theta \quad \frac{\partial z}{\partial \theta} = -r \sin \theta \quad \frac{\partial z}{\partial \varphi} = 0$$

$$H_r = 1 \quad H_\theta = r \quad H_\varphi = r \sin \theta$$

$$g_{\mu\nu} = \begin{pmatrix} r^2 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$


$$\Gamma_{rr}^r = 0 \quad \Gamma_{r\theta}^r = 0 \quad \Gamma_{r\varphi}^r = 0 \quad \Gamma_{\theta\theta}^\theta = 27 \text{ 个}$$

$$\Gamma_{\theta r}^\theta = 0 \quad \Gamma_{\theta\theta}^\theta = 0 \quad \Gamma_{\theta\varphi}^\theta = 0$$

$$\Gamma_{\varphi r}^\varphi = 0 \quad \Gamma_{\varphi\theta}^\varphi = 0 \quad \Gamma_{\varphi\varphi}^\varphi = 0$$

$$\Gamma_{\varphi r}^\varphi = 0 \quad \Gamma_{\varphi\theta}^\varphi = 0 \quad \Gamma_{\varphi\varphi}^\varphi = 0$$

$$\Gamma_{\theta\theta}^\theta = 27 \text{ 个} \quad \Gamma_{\varphi\varphi}^\varphi = 27 \text{ 个}$$

$$\Gamma_{r\alpha}^\alpha = \frac{1}{2} g^{\alpha\beta} (g_{\beta\alpha,r} + g_{\alpha\beta,r} - g_{r\alpha,\beta})$$

$$= \frac{1}{2} g^{\alpha\alpha} (g_{\alpha\alpha,r} + g_{\alpha\alpha,r} - g_{r\alpha,\alpha})$$

$$= \frac{1}{2} g^{\alpha\alpha} g_{\alpha\alpha,r}$$

$$\Gamma_{\theta r}^\theta = \frac{1}{2} g^{\theta\theta} g_{\theta\theta,r} = \frac{1}{2} g^{\theta\theta} g_{\theta\theta,r} = 0$$

$$\Gamma_{r\theta}^\theta = \frac{1}{2} g^{\theta\theta} g_{\theta\theta,r} = r/r^2 = 1/r$$

$$\Gamma_{r\varphi}^\varphi = \frac{1}{2} g^{\varphi\varphi} g_{\varphi\varphi,r} = r \sin^2 \theta / r^2 \sin \theta = 1/r$$

共 15 个

$$\Gamma_{rj}^i \quad (i, j \neq r, i \neq j)$$

$$\Gamma_{rj}^i = \frac{1}{2} g^{i\beta} (g_{\beta r,j} + g_{j\beta,r} - g_{rj,\beta})$$

$$= \frac{1}{2} g^{ii} (g_{ri,j} + g_{ji,r} - g_{rj,i})$$

$$= 0$$

共 13 个

$$\xi_r = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$$

$$\xi_\theta = r (-\sin \theta \cos \varphi, -\sin \theta \sin \varphi, \cos \theta)$$

$$\xi_\varphi = r (-\sin \theta \sin \varphi, \sin \theta \cos \varphi, 0)$$

$$\xi^r = g^{rr} \xi_r = \xi_r = \dots$$

$$\xi^\theta = g^{\theta\theta} \xi_\theta = \frac{1}{r} (\dots)$$

$$\xi^\varphi = g^{\varphi\varphi} \xi_\varphi = \frac{1}{r \sin \theta} (\dots)$$

$$\vec{r} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (*)$$

$$\frac{\partial}{\partial p} \begin{bmatrix} \frac{\partial A_0}{\partial p} + 0 & \frac{\partial A_0}{\partial p} + 0 & \frac{\partial A_0}{\partial p} + 0 \\ \frac{\partial}{\partial \theta} \frac{\partial A_0}{\partial \theta} & \frac{\partial}{\partial \theta} \frac{\partial A_0}{\partial \theta} + \frac{A_0}{p} & \frac{\partial}{\partial \theta} \frac{\partial A_0}{\partial \theta} \\ \frac{\partial}{\partial \phi} \frac{\partial A_0}{\partial \phi} & \frac{\partial}{\partial \phi} \frac{\partial A_0}{\partial \phi} + \frac{1}{p \sin \theta} \frac{\partial A_0}{\partial \phi} & \frac{\partial}{\partial \phi} \frac{\partial A_0}{\partial \phi} + \frac{A_0}{p} \end{bmatrix}$$

$$\nabla_\mu A_\nu^* = \frac{\partial A_\nu}{\partial q^\mu} - A_\rho \Gamma_{\mu\nu}^\rho$$

	$A_1$	$A_2$	$A_3$
$\frac{\partial}{\partial q^1}$	0	0	0
$\frac{\partial}{\partial q^2}$	0	0	0
$\frac{\partial}{\partial q^3}$	0	0	0

$$\frac{d(\det(g))}{dq^k} = \det(g) g^{im} \frac{\partial g_{im}}{\partial q^k}$$

$$\Gamma_{ik}^i = \frac{1}{2 \det(g)} \frac{d \det(g)}{dq^k} = \frac{1}{\sqrt{|g|}} \frac{\partial \sqrt{|g|}}{\partial q^k}$$

$$\Rightarrow \nabla \cdot \vec{V} = V_i{}^i = \frac{1}{\sqrt{|g|}} \frac{\partial}{\partial q^k} (\sqrt{|g|} V^k)$$

Laplacian

$$g^{ki} \frac{\partial \psi}{\partial q^i} \rightarrow \nabla \cdot \vec{V}$$

$$\nabla^2 \psi = \left[ \frac{\partial^2}{\partial x^2} \dots \right]$$

$$= \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial q^i} \left( \frac{h_1 h_2 h_3}{h_i^2} \frac{\partial \psi}{\partial q^i} \right)$$

Curl

$$\frac{\partial V_i}{\partial q^j} - \frac{\partial V_j}{\partial q^i} = \frac{\partial V_i}{\partial q^j} - V_k \Gamma_{ij}^k - V_j \Gamma_{ik}^k - V_k \Gamma_{ji}^k = V_i{}^j - V_j{}^i$$

Tensor Derivative Operator

Gradient  $\nabla \psi = \frac{\partial \psi}{\partial q^i} \hat{e}_i$

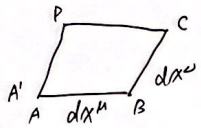
Divergence  $\nabla \cdot \vec{V} = \hat{e}^j \cdot \frac{\partial (V_i \hat{e}_i)}{\partial q^j} = \hat{e}^j \cdot \left( \frac{\partial V_i}{\partial q^j} + \Gamma_{jk}^i V_k \right) \hat{e}_i = \frac{\partial V_i}{\partial q^i} + \dots$

$$\Gamma_{ik}^i = \frac{1}{2} g^{im} \left[ \frac{\partial g_{im}}{\partial q^k} + \frac{\partial g_{km}}{\partial q^i} - \frac{\partial g_{ik}}{\partial q^m} \right] = \frac{1}{2} g^{im} \frac{\partial g_{im}}{\partial q^k} \Gamma_{ik}^i$$

Jacobian

$$\begin{pmatrix} \frac{dx_1}{du_1} \\ \vdots \\ \frac{dx_n}{du_n} \end{pmatrix} = \begin{pmatrix} \frac{\partial x_1}{\partial u_1} & \frac{\partial x_1}{\partial u_2} & \frac{\partial x_1}{\partial u_3} \\ \vdots & \vdots & \vdots \\ \frac{\partial x_n}{\partial u_1} & \frac{\partial x_n}{\partial u_2} & \frac{\partial x_n}{\partial u_3} \end{pmatrix} \begin{pmatrix} \frac{\partial u_1}{\partial x} \\ \frac{\partial u_2}{\partial x} \\ \frac{\partial u_3}{\partial x} \end{pmatrix}$$

Introduction to GR



$$dV = V_B - V_A' = [(V_C - V_D) - (V_B - V_A)] - [(V_C - V_D) - (V_B - V_A)']$$

$$= \int \nabla_\nu dx^\mu \nabla_\mu dx^\nu V = \nabla_\mu dx^\mu \nabla_\nu dx^\nu V$$

$$= dx^\mu dx^\nu V [\nabla_\nu, \nabla_\mu]$$

$$[\nabla_\nu, \nabla_\mu]$$

$$= (\partial_\nu + \Gamma_{\nu\alpha}^\alpha)(\partial_\mu + \Gamma_{\mu\beta}^\beta) - (\partial_\mu + \Gamma_{\mu\alpha}^\alpha)(\partial_\nu + \Gamma_{\nu\beta}^\beta)$$

$$= (\partial_\nu \partial_\mu + \Gamma_{\nu\alpha}^\alpha \partial_\mu + \partial_\nu \Gamma_{\mu\beta}^\beta + \Gamma_{\nu\alpha}^\alpha \Gamma_{\mu\beta}^\beta) - (\partial_\mu \partial_\nu + \partial_\mu \Gamma_{\nu\beta}^\beta + \Gamma_{\mu\alpha}^\alpha \partial_\nu + \Gamma_{\mu\alpha}^\alpha \Gamma_{\nu\beta}^\beta)$$

$$= -[\partial_\mu, \Gamma_{\nu\alpha}^\alpha] + [\partial_\nu, \Gamma_{\mu\beta}^\beta] + [\Gamma_{\nu\alpha}^\alpha, \Gamma_{\mu\beta}^\beta]$$

$$= -\frac{\partial \Gamma_{\nu\alpha}^\alpha}{\partial x^\mu} + \frac{\partial \Gamma_{\mu\beta}^\beta}{\partial x^\nu} + [\Gamma_{\nu\alpha}^\alpha, \Gamma_{\mu\beta}^\beta] = R_{\mu\nu}$$

$$R = g^{\mu\nu} R_{\mu\nu}$$

$$\nabla_\rho R = \nabla_\rho (g^{\mu\nu} R_{\mu\nu}) + g^{\mu\nu} \nabla_\rho R_{\mu\nu}$$

$$= g^{\mu\nu} \nabla_\rho (R_{\mu\nu})$$

$$g_{\mu\nu} \nabla_\rho R = g$$

$$= g_{\rho\sigma} g^{\mu\nu} \nabla_\rho (R_{\mu\nu}) = g_{\rho\sigma} \nabla_\rho R = \nabla_\rho R g_{\rho\sigma}$$

$$\nabla_\tau \frac{dx^\mu}{d\tau} = 0$$

$$\frac{\partial^2 x^\mu}{\partial \tau^2} = -\Gamma \approx F$$

$$\Rightarrow \frac{\partial}{\partial \tau} \frac{\partial x^\mu}{\partial \tau} + \Gamma = 0$$

$$\Gamma = \frac{1}{2} g^{\alpha\beta} ( \dots )$$

$$= \frac{1}{2} \frac{\partial g_{00}}{\partial x} \equiv \Gamma = -\frac{\partial \phi}{\partial x}$$

$$g_{00} \approx 2\phi + c$$

$$\nabla^2 \phi = 4\pi G \rho$$

$$\nabla^2 g_{00} = 8\pi G \rho$$

$$G_{\mu\nu} = 8\pi G T_{\mu\nu}$$

$$R_{\mu\nu} = 8\pi G T_{\mu\nu}$$

$$\nabla^\mu T_{\mu\nu} = 0$$

$$\nabla^\mu R_{\mu\nu} \neq 0$$

$$\text{But } \nabla_\mu (R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R) = 0$$

$$\nabla_\nu (R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R + \Lambda g_{\mu\nu}) = 0$$

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R + \Lambda g_{\mu\nu} = \frac{8\pi G T_{\mu\nu}}{c^4}$$

$$[\nabla_\mu, [\nabla_\nu, \nabla_\lambda]] + [\nabla_\nu, [\nabla_\lambda, \nabla_\mu]] + [\nabla_\lambda, [\nabla_\mu, \nabla_\nu]] = 0$$

Riemann Identity

$$R_{abm;l} + R_{abln;m} + R_{ablm;n} = 0$$

$$g^m g^{an} ( \dots ) = 0$$

$$g^m (R^m{}_{bml;n} + R^m{}_{bnl;n} + R^m{}_{nbl;m}) = 0$$

$$R^m{}_{n;l} - R^m{}_{l;n} - R^m{}_{nl;m} = 0$$

$$R_{;l} - R^m{}_{l;n} - R^m{}_{l;m} = 0$$

$$R_{;l} = 2R^m{}_{;l;m}$$

$$\Rightarrow \nabla_\lambda R^{\rho\sigma} = \frac{1}{2} \nabla_\mu R$$

# Differential forms

## 1. Introduction $dx \ dy \ dz$

$$w = A dx + B dy + C dz \quad 1\text{-form}$$

$$w = F dx \wedge dy + G dx \wedge dz + H dy \wedge dz \quad 2\text{-form}$$

$$w = K dx \wedge dy \wedge dz \quad 3\text{-form}$$

## Exterior algebra (Grassmann Algebra)

$p$ -form,  $p$  factors  $dx_i$ , no  $dx_i$ ,  $0$ -form

## 2. Exterior algebra

$$(aw_1 + bw_2) \wedge w_3 = aw_1 \wedge w_3 + bw_2 \wedge w_3 \quad (p_1 = p_2)$$

$$(w_1 \wedge w_2) \wedge w_3 = w_1 \wedge (w_2 \wedge w_3)$$

$$a(w_1 \wedge w_2) = (aw_1) \wedge w_2$$

$$dx_i \wedge dx_j = -dx_j \wedge dx_i$$

$$a dx_i \wedge b dx_j = -a(b dx_j \wedge dx_i) = -ab(dx_j \wedge dx_i) = ab dx_i \wedge dx_j$$

$$\sum_p dx_{h_1} \wedge dx_{h_2} \wedge \dots \wedge dx_{h_p} \quad 1 \leq h_1 < h_2 < \dots < h_p$$

$$p \leq d$$

## Example

$$w = (3dx + 4dy - dz) \wedge (dx - dy + 2dz)$$

$$= 7(dy \wedge dz - dz \wedge dx - dx \wedge dy)$$

Complementary (Dual) DF.  $\star$  operator  
 $d$ ,  $p$ -form  $\downarrow$   $(d-p)$ -form Hodge operator  
 Metric / orientation. [Orthogonal]

- $\star w$  1. (indices of  $w$ ) followed by (indices of  $w'$ )
- 2.  $(-1)^m$  (Metric tensor diagonal element)

## 3D - Euclidean

$$\star 1 = dx_1 \wedge dx_2 \wedge dx_3$$

$$\star dx_i = dx_j \wedge dx_k \quad \dots$$

$$\star(dx_i \wedge dx_j) = dx_k$$

$$\star(dx_i \wedge dx_j \wedge dx_k) = 1$$

$$\star(\star w) = w$$

## Example 4D - Minkowski

$$\begin{pmatrix} 1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \end{pmatrix}$$

$$\star 1 = dt \wedge dx \wedge dy \wedge dz$$

$$\star(dt \wedge dx \wedge dy \wedge dz) = -1$$

$$\star dx_i = dt \wedge dx_j \wedge dx_k, \quad \star dx_i = dt \wedge dx_j \wedge dx_k$$

$$\star(dt \wedge dx_i) = -dx_j \wedge dx_k, \quad \star(dt \wedge dx_i) = -dx_j \wedge dx_k$$

$$A = A_x dx + A_y dy + A_z dz \Rightarrow A \wedge B = (A_y B_z - A_z B_y) dy \wedge dz + \dots$$

$$\star(A \wedge B) = (A_y B_z - A_z B_y) dx + \dots$$

$$= (\vec{A} \times \vec{B})_x dx + \dots$$

$$A \wedge B \wedge C = (A_x B_y C_z - \dots) dx \wedge dy \wedge dz$$

$$\star(A \wedge B \wedge C) = \vec{A} \cdot (\vec{B} \times \vec{C})$$



Exterior Derivatives

$$d(w+w') = dw + dw' \quad \text{if } w = w'$$

$$d(fw) = (df) \wedge w + f dw$$

$$d(w \wedge w') = dw \wedge w' + (-1)^p w \wedge dw'$$

$$d(dw) = 0$$

$$df = \sum_j \frac{\partial f}{\partial x_j} dx_j$$

Example

$$w = A dx_1 \wedge \dots \wedge dx_p \quad dw = \sum_{\mu} \frac{\partial A}{\partial x_{\mu}} dx_{\mu} \wedge \dots$$

$$w' = B dx_1 \wedge \dots \wedge dx_p' \quad dw' = \sum_{\mu} \frac{\partial B}{\partial x_{\mu}} dx_{\mu} \wedge \dots$$

$$d(w \wedge w') = d(AB) [dx_1 \wedge \dots \wedge dx_p] \wedge [dx_1 \wedge \dots \wedge dx_p']$$

$$= \sum_{\mu} \left[ \frac{\partial A}{\partial x_{\mu}} B + A \frac{\partial B}{\partial x_{\mu}} \right] dx_{\mu} \wedge [ \dots ] \wedge [ \dots ]$$

$$= dw \wedge w' + (-1)^p w \wedge dw'$$

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

$$d(df) = \frac{\partial}{\partial x} \left( \frac{\partial f}{\partial x} \right) dx \wedge dx + \dots$$

$$+ \frac{\partial}{\partial y} \left( \frac{\partial f}{\partial x} \right) dy \wedge dx + \frac{\partial}{\partial x} \left( \frac{\partial f}{\partial y} \right) dx \wedge dy = 0$$

~~df~~  $\Rightarrow df = (\nabla f)_x dx + \dots$

$$dw = d(Ax dx + Ay dy + Az dz) \quad \textcircled{1}$$

$$= \left( \frac{\partial Ax}{\partial x} dx + \frac{\partial Ax}{\partial y} dy + \frac{\partial Ax}{\partial z} dz \right) \wedge dx + \dots$$

$$= \left[ \frac{\partial Ax}{\partial y} - \frac{\partial Ay}{\partial x} \right] dy \wedge dx + \dots$$

$$= (\nabla \times A)_x dy \wedge dz$$

$$* d(Ax dx + By dy + Az dz) = (\nabla \times A)_x dx + \dots$$

$$d(B_x dy \wedge dz + B_y dz \wedge dx + B_z dx \wedge dy)$$

$$= \left( \frac{\partial B_x}{\partial x} dx + \dots \right) \wedge dy \wedge dz + \dots$$

$$= \left[ \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} \right] dx \wedge dy \wedge dz$$

$$\Rightarrow *d(\dots) = \nabla \cdot \vec{B} \quad \textcircled{2}$$

in ① Let  $w = df$

$$d(df) = (\nabla \times \nabla f)_x dy \wedge dz + \dots = 0$$

in ②  $*d(B) = d(Ax dx + \dots)$

$$d(d(Ax dx + \dots)) = \nabla \cdot (\nabla \times A) dx \wedge dy \wedge dz = 0$$

Example

$$F_{\mu\nu} = \begin{pmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -B_z & B_y \\ -E_y & B_z & 0 & -B_x \\ -E_z & -B_y & B_x & 0 \end{pmatrix}$$

$$F = -E_x dt \wedge dx - E_y dt \wedge dy - E_z dt \wedge dz$$

$$+ B_x dy \wedge dz + B_y dz \wedge dx + B_z dx \wedge dy$$

$$J = \rho dx \wedge dy \wedge dz - J_x dt \wedge dy \wedge dz - J_y dt \wedge dz \wedge dx - J_z dt \wedge dx \wedge dy$$

$$dF = 0 \Rightarrow$$

$$*F = \dots$$

$$d(*F) = -\vec{J} \Rightarrow$$

$$\left. \begin{array}{l} dJ = 0 \Rightarrow \\ \text{(Bianchi Identi)} \end{array} \right\} d(*F) = \vec{J}$$

Integrating forms.

1-form

$$\int_c w = \int_c [A_x dx + A_y dy] = \int_{t_p}^{t_Q} [A_x(t) \frac{dx}{dt} + A_y(t) \frac{dy}{dt}] dt$$

If it's independent about  $P \sim Q$ ,  
 $w$  is exact,  $w = df(x, y)$

$$\int_P^Q w = df, \quad w = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

$$\Rightarrow \int_P^Q w = f(Q) - f(P)$$

$$\int_S w = \int_S v(x, y) dx \wedge dy$$

$$x = au + bv, \quad y = cu + dv$$

$$dx \wedge dy = \dots (af - be) du \wedge dv$$

Stokes' Theorem

Simply connected region  $R$  of  $p$ -d differentiable manifold  
 in  $n$ -d space.

$R$  has a boundary  $\partial R$ ,  $d$  is  $p-1$

$w$  is a  $(p-1)$  form defined on  $R$  and boundary,  
 with derivative  $dw$

then

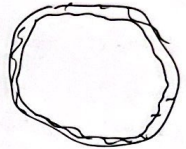
$$\int_R dw = \int_{\partial R} w$$

$$w = A dx_1 \wedge \dots \wedge dx_p$$

$$dw = \frac{\partial A}{\partial x_1} dx_1 \wedge dx_2 \wedge \dots \wedge dx_p$$

$$\int_S dw = \int_{\partial S} \left( \frac{\partial A}{\partial x_1} \right) dx_1 \wedge \dots \wedge dx_p$$

$$= \int_{\partial S} A(x_1, \dots) dx_1 \wedge \dots \wedge dx_p - \int_{\partial S} A(x_1, \dots) dx_2 \wedge \dots \wedge dx_p$$



Example: Green's Theorem in Plane

$$w = P dx + Q dy$$

$$dw = \frac{\partial P}{\partial y} dy \wedge dx + \frac{\partial Q}{\partial x} dx \wedge dy$$

$$= \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx \wedge dy$$

$$\Rightarrow \int_C (P dx + Q dy) = \int_S \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dS$$

$$w = A_x dx + A_y dy + A_z dz$$

$$dw = \dots$$

$$\int_C A_x dx + \dots = \int_C \vec{A} \cdot d\vec{r} = \int_S (\nabla \times \vec{A}) \cdot d\vec{\sigma}$$

$$w = E_x dy \wedge dz + E_y dz \wedge dx + \dots$$

$$dw = \left( \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \dots \right) dx \wedge dy \wedge dz$$

$$\Rightarrow \int (\nabla \cdot \vec{E}) d\tau = \int_V \vec{E} \cdot d\vec{\sigma}$$