

ϕ^4

we have prove that

$$Z[J] = N \exp \left[i \int \mathcal{L}_{int} \left(\frac{1}{i} \frac{\delta}{\delta J} \right) dx \right] Z_0[J]$$

$$\mathcal{L}_{int} = -\frac{g}{4!} \phi^4$$

$$Z[J] = \frac{\exp \left[i \int \mathcal{L}_{int} \left(\frac{1}{i} \frac{\delta}{\delta J} \right) dz \right] \exp \left[-\frac{i}{2} \int J(x) \Delta_F(x-y) J(y) dx dy \right]}{\left[\exp \left[-\frac{i}{2} \int J(x) \Delta_F(x-y) J(y) dx dy \right] \right]_{J=0}}$$

$$\left[1 - \frac{ig}{4!} \int \left(\frac{1}{i} \frac{\delta}{\delta J} \right)^4 dz + \dots \right] \exp \left[-\frac{i}{2} \int J(x) \Delta_F(x-y) J(y) dx dy \right]$$

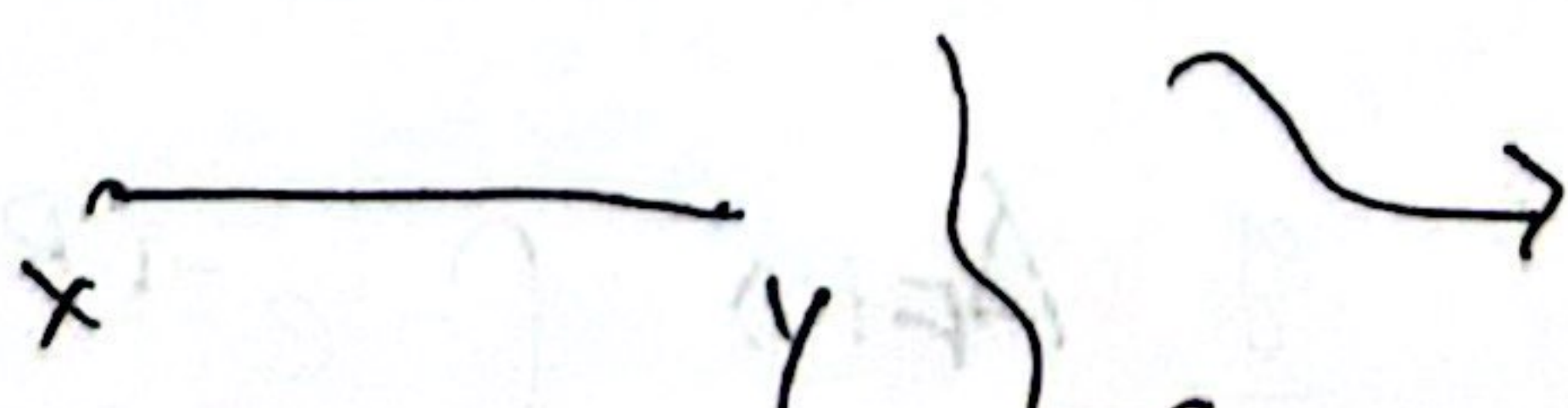
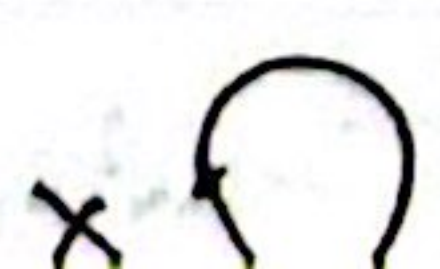
To order 0, free $Z_0[J]$,to order g ,

$$\frac{1}{i} \frac{\delta}{\delta J(z)} \exp [] = - \int \Delta_F(z-x) J(x) dx \exp []$$

$$\left(\frac{1}{i} \frac{\delta}{\delta J} \right)^2 \exp [] = \left\{ i \Delta_F(0) + \left[\int \Delta_F(z-x) J(x) dx \right]^2 \right\} \exp []$$

$$\left(\frac{1}{i} \frac{\delta}{\delta J} \right)^3 \exp [] = \left\{ 3 [-i \Delta_F(0)] \int \Delta_F(z-x) J(x) dx - \left[\int \Delta_F(z-x) J(x) dx \right]^3 \right\} \times \exp []$$

$$\left(\frac{1}{i} \frac{\delta}{\delta J} \right)^4 \exp [] = \left\{ -3 [\Delta_F(0)]^2 + 6i \Delta_F(0) \left[\int \Delta_F(z-x) J(x) dx \right]^2 + \left[\int \Delta_F(z-x) J(x) dx \right]^4 \right\} \times \exp []$$

 $\Delta_F(x-y)$  $\Delta_F(0)$ 

$$\left\{ -3 \infty + 6i \times \text{circle} + \left\{ \begin{array}{c} \times \\ \times \end{array} \right\} \right\} \times \exp []$$

$$\text{exp } \frac{g}{4!} = 1 - \frac{ig}{4!} \int (-300) dz$$

$$Z[J] = \frac{\left[1 - \frac{ig}{4!} \int (-300 + 6i \cancel{x \circ x} + \cancel{x \times x}) dz \right] \times \text{exp}}{1 - \frac{ig}{4!} \int -300 dz}$$

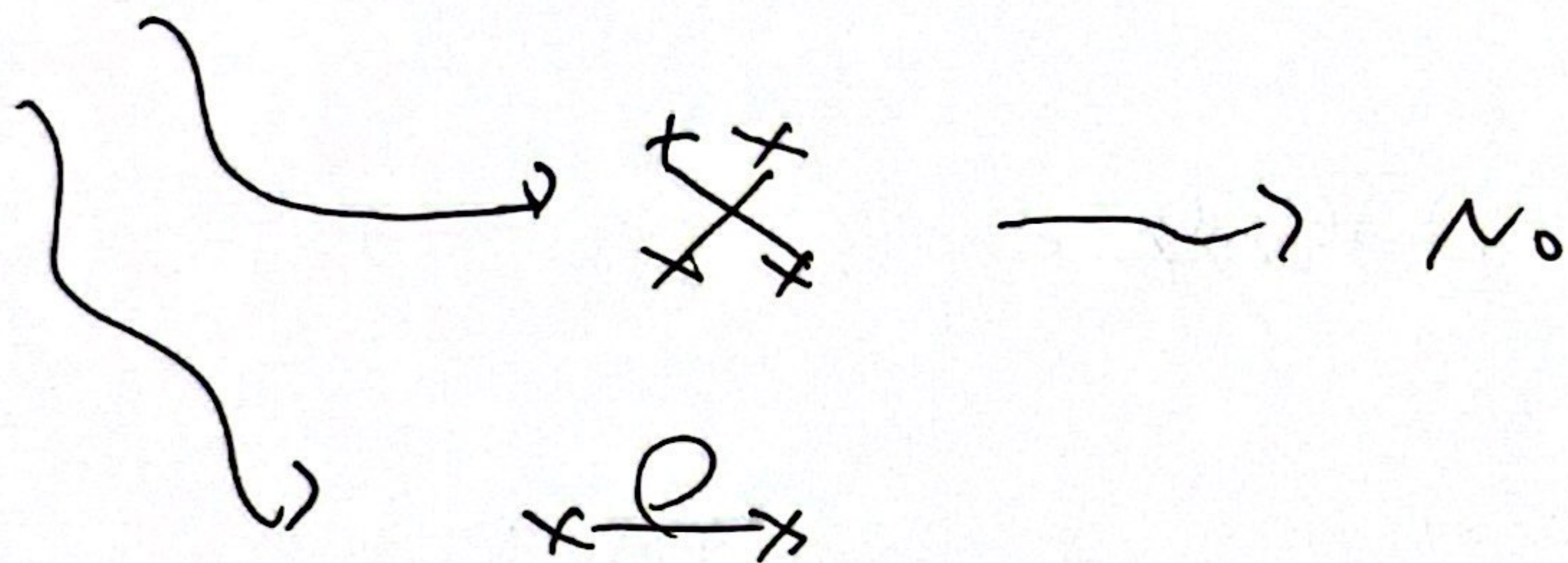
$$= \left[1 - \frac{ig}{4!} \int (6i \cancel{x \circ x} + \cancel{x \times x}) dz \right] \times \text{exp}$$

∞ disappear!

2-point func.

$$\tau(x_1, x_2) = - \frac{\delta^2 Z[J]}{\delta J(x_1) \delta J(x_2)} \Big|_{J=0}$$

$$Z[J] \rightsquigarrow 1 \rightarrow i \Delta_F(x_1 - x_2)$$



$$\frac{g}{4} \Delta_F(0) \int dx dy dz \Delta_F(z-x) J(x) \Delta_F(z-y) J(y) \exp(\dots)$$

$$= - \frac{g}{2} \Delta_F(0) \int dz \Delta_F(z-x_1) \Delta_F(z-x_2)$$

$$\tau(x_1, x_2) = i \text{---} - \frac{g}{2} \text{---} + \dots$$

$$i \frac{1}{(2\pi)^4} \int \frac{e^{-ik(x-y)}}{k^2 - m^2 + i\epsilon} d^4k$$

\rightsquigarrow renormalization

$$- \frac{1}{2} g \Delta_F(0) \int \Delta_F(x-z) \Delta_F(x_2-z) dz = - \frac{g}{2} \frac{\Delta_F(0)}{(2\pi)^8} \int \frac{e^{-iP(x_1-z)}}{p^2 - m^2 + i\epsilon} \frac{e^{-iQ(x_2-z)}}{q^2 - m^2 + i\epsilon} d^4p d^4q$$

$$\begin{aligned}
 \tau(x_1, x_2) &= -\frac{g}{2} \frac{\Delta_F(0)}{(2\pi)^4} \int \frac{e^{-ip(x_1-x_2)}}{(p^2-m^2+i\epsilon)^2} dp dq \delta^4(p+q) \\
 &= -\frac{g}{2} \frac{A_F(0)}{(2\pi)^4} \int \frac{e^{-ip(x_1-x_2)}}{(p^2-m^2+i\epsilon)^2} dp.
 \end{aligned}$$

$$\begin{aligned}
 \tau(x_1, x_2) &= \frac{i}{(2\pi)^4} \int \frac{e^{-ip(x_1-x_2)}}{p^2-m^2+i\epsilon} \left[1 + \frac{\frac{i}{2} g A_F(0)}{p^2-m^2+i\epsilon} \right] d^4p. \\
 &= \frac{i}{(2\pi)^4} \int \frac{e^{-ip(x_1-x_2)}}{p^2-m^2 - \frac{1}{2} i g A_F(0) + i\epsilon} dp.
 \end{aligned}$$

$$m^2 + \frac{1}{2} i g A_F(0) = m_r^2 \quad \text{physical mass}$$

$$\Delta m^2 = \frac{1}{2} i g A_F(0).$$

↑
divergent!

4-point.

$$\tau(x_1, x_2, x_3, x_4) = \frac{\delta^4 Z[J]}{\delta J(x_1) \delta J(x_2) \delta J(x_3) \delta J(x_4)} \Big|_{J=0}$$

$$\textcircled{1} \quad \begin{aligned}
 &= -3(\text{---}) + \dots \\
 &\frac{g}{4} \int d^4z \frac{\delta^4 Z[J]}{\delta J(x_1) \delta J(x_2) \delta J(x_3) \delta J(x_4)} \left\{ \Delta_F(0) \int dx dy dz \Delta_F(x-z) \Delta_F(x-z) J(y) J(x) \exp \right\} \Big|_{J=0}
 \end{aligned}$$

$$= \frac{-ig}{2} \Delta_F(0) \int dz \left[\Delta_F(z-x_1) \Delta_F(z-x_2) \Delta_F(x_3-x_4) + \dots \right]$$

$$= -3ig \left[\text{---} \right]$$

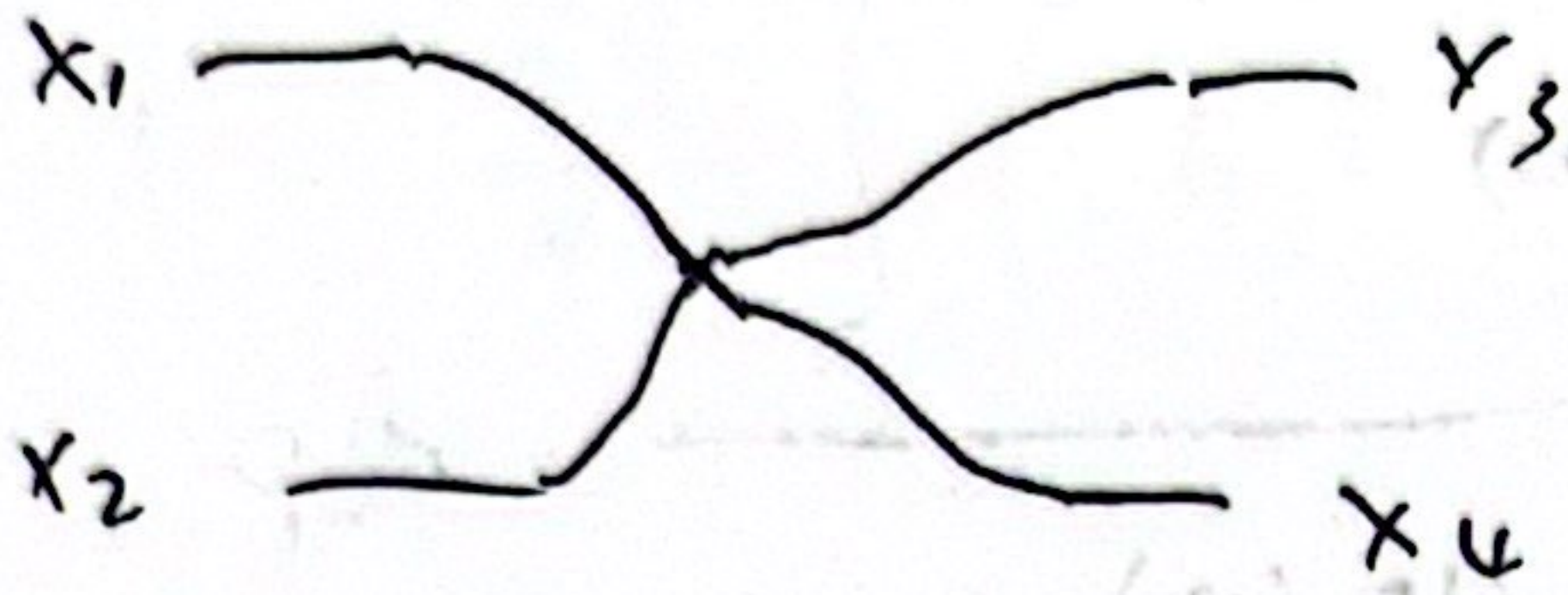
$$\textcircled{2} \quad \begin{aligned}
 &\frac{-ig}{4} \int d^4z \left\{ \dots \exp \right\} \Big|_{J=0} = -ig \times
 \end{aligned}$$

$$\tau(x_1, x_2, x_3, x_4)$$

$$= -3 [\text{=}] - \frac{i g}{4!} [12 \times 6 \left(\text{=} \right) + 24 (X)]$$

Diagram g' x

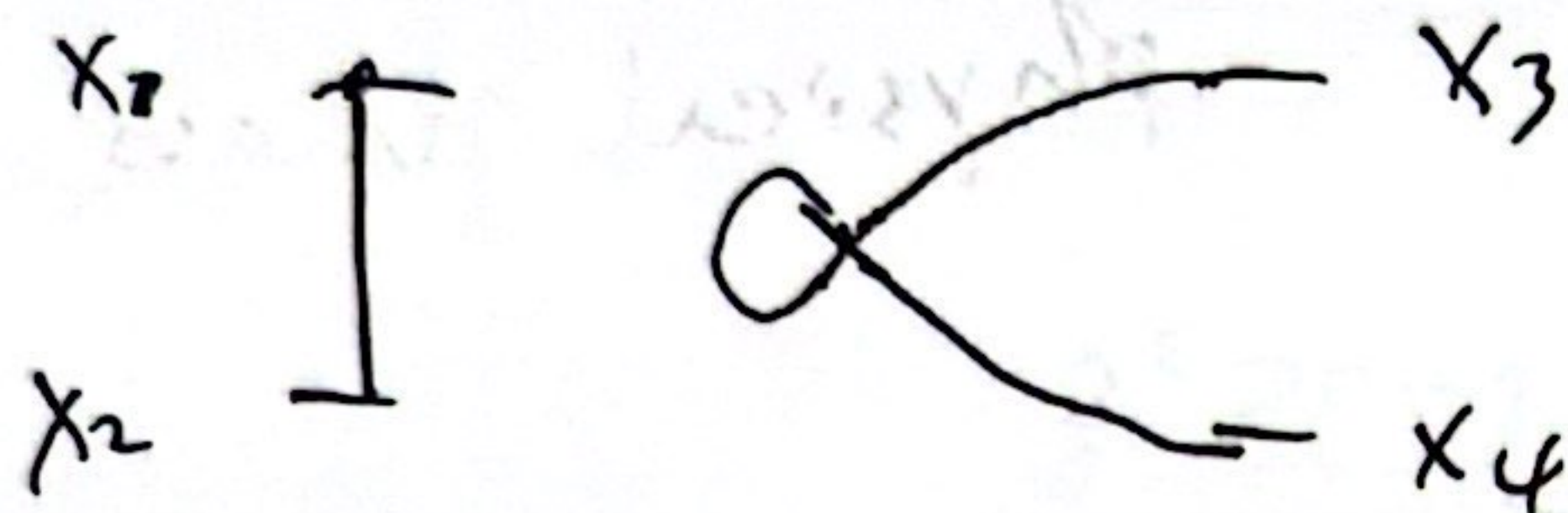
①



$$4 \times 3 \times 2 \times 1 = 24$$

$$3 \times 4 \times 2 \times 3 = 12 \times 6$$

②



$$4 \times 3 \times 2 \times 1 = 24$$

$$= 12 \times 6$$

③



$$3 \times 3 = 9$$

Coordinate space

In S -matrix

line.



$$A = (x-y)$$

trivial part

Vertex

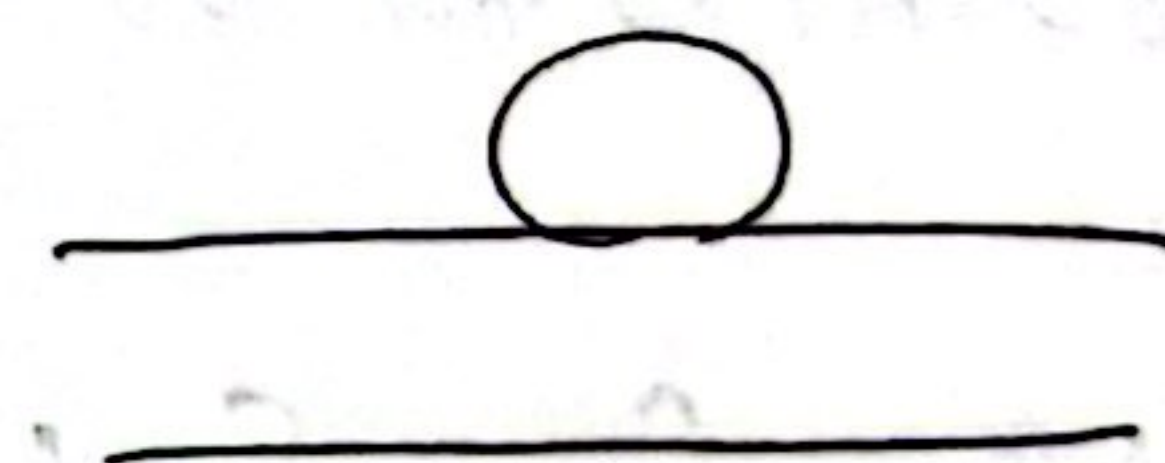
$$x^2$$

$$-i g$$

disconnected

Symmetry factor

$$S/4!$$



non trivial

connected

Connected diagram generating functional.

$$Z[J] = e^{iW[J]}$$

like free energy X

$$W[J] = -i \ln Z[J]$$

$$\frac{\delta^2 W}{\delta J(x) \delta J(x')} = \frac{i}{Z^2} \frac{\delta^2 Z}{\delta J(x) \delta J(x')} = \frac{i}{Z} \frac{\delta^2 Z}{\delta J(x) \delta J(x')}$$

$$= 2 \left[\left(i \begin{array}{c} 1 \quad 2 \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} - \frac{g}{2} \begin{array}{c} \bigcirc \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} \right) \left(i \begin{array}{c} 3 \quad 4 \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} - \frac{g}{2} \begin{array}{c} \bigcirc \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} \right) \right. \\
+ \dots + \dots$$

$$+ \left(\begin{array}{c} 1 \quad 2 \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} + \dots \right)$$

$$+ \left(\frac{ig}{2} \begin{array}{c} 1 \quad 2 \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} + \dots \right)$$

$$+ \frac{ig}{4!} \begin{array}{c} 1 \quad 2 \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} + \dots$$

Zinn-Justin

$$= - \frac{g}{4!} \left(\begin{array}{c} 1 \quad 2 \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array} + \dots \#24 \right) = -gX$$

$$\tau(x_1, \dots, x_n) = \frac{1}{i^n} \frac{\delta^n Z}{\delta(x_1, \dots, x_n)} \Big|_{J=0}$$

$$\phi(x_1, \dots, x_n) = \frac{1}{i^n} \frac{\delta^n W}{\delta(x_1, \dots, x_n)} \Big|_{J=0} \quad \text{irreducible.}$$

$$\tau(x_1, \dots, x_4) = \underbrace{-igX}_{\text{tree}} - \underbrace{3ig \begin{array}{c} \bigcirc \\ \diagdown \quad / \\ \diagup \quad \diagdown \end{array}}_{\text{loop}} - 3 = \dots$$

$$i\phi(x_1, \dots, x_4) = -igX$$

$$\tau(x_1, \dots, x_4) = i\phi(x_1, \dots, x_4) - \sum_P \phi(x_{i_1}, x_{i_2}) \phi(x_{i_3}, x_{i_4})$$

